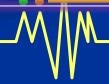
Model fidelity & Simple energetics based study on Monsoon Lows and Depressions

Partha Mukhopadhyay, (mpartha@tropmet.res.in)

Sahadat Sarkar¹, R. Phani Murali krishna¹, Dr. Somenath Dutta²

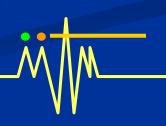
1. Indian Institute of Tropical Meteorology, Pune-411008, India 2. India Met. Dept. New Delhi



Outline

- Background
- Monsoon Depressions and Monsoon lows and transition
- · Model fidelity
- Conclusion





Tropical Cyclone Hazard to Mumbai in the Recent Historical Climate®

ADAM H. SOBEL, CHIA-YING LEE, SUZANA J. CAMARGO, AND KYLE T. MANDLI Columbia University, New York, New York

KERRY A. EMANUEL

Massachusetts Institute of Technology, Cambridge, Massachusetts

PARTHASARATHI MUKHOPADHYAY AND M. MAHAKUR

Indian Institute of Tropical Meteorology, Pune, Maharashtra, India

(Manuscript received 30 November 2018, in final form 17 April 2019)

Bombay Cyclone of 1882 (hoax)

The so-called **Bombay Cyclone of 1882** or **Great Bombay Cyclone** is a hoax (or otherwise fictitious) historical event. Supposedly, the cyclone struck Bombay on 6 June 1882. Though it is widely reported, even in scientific literature, historical research shows that it did not in fact happen.

Example accounts of the supposed event

Reportedly, the earliest mention of the supposed cyclone so far discovered by researchers is in a newspaper called *Telegraph* on 17 September 1947.^[1] The cyclone is mentioned in academic literature from at least 1976.^[2] Its entry in the 2008 edition of the *Encyclopedia of Hurricanes*, *Typhoons*, and *Cyclones* reads:

The Great Bombay Cyclone of June 6, 1882: One of few truly great Indian cyclones to have formed over the Arabian Sea, the Great Bombay Cyclone--engorged with 110-MPH (177-km/h) winds and an 18-foot (6-m) surge--reportedly claimed more than 100,000 lives when it came ashore at Bombay right before daybreak.^[3]

A 2014 academic article claims that: 'the deadliest storm surge of Arabian sea was Great Bombay Cyclone, took place in 1882 causing 100,000 causalities [sic]. It is one of ten deadliest tropical cyclones of the known history of the world'. [4] Another account, published in 2017, says that

the city of Bombay was all but destroyed by a monster cyclone that slammed into the Maharashtra region on June 6th 1882. This was one of the few great storms to emerge from the Arabian Sea. The super storm covered an enormous area as it came ashore at dawn bringing with it 110 mile per hour winds and an 18 foot tidal surge that inundated much of the region around Bombay ... The resultant winds, flooding and damage to buildings killed more the 100,000 people. [5]

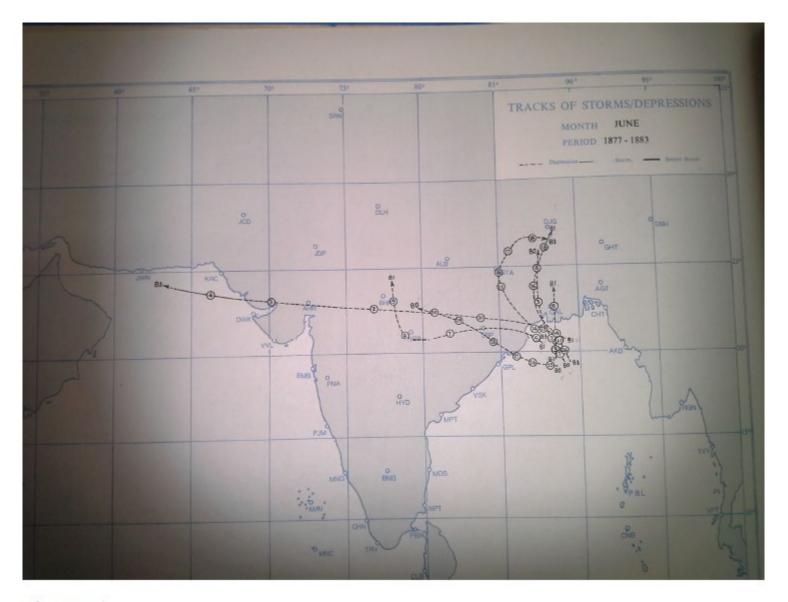
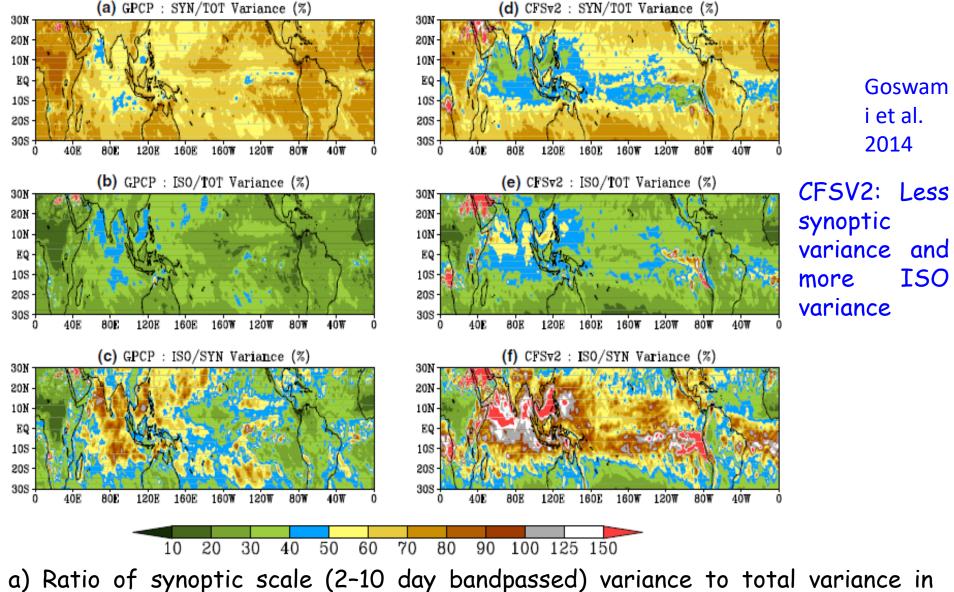


Fig. S1, a) Sobel et al 2019



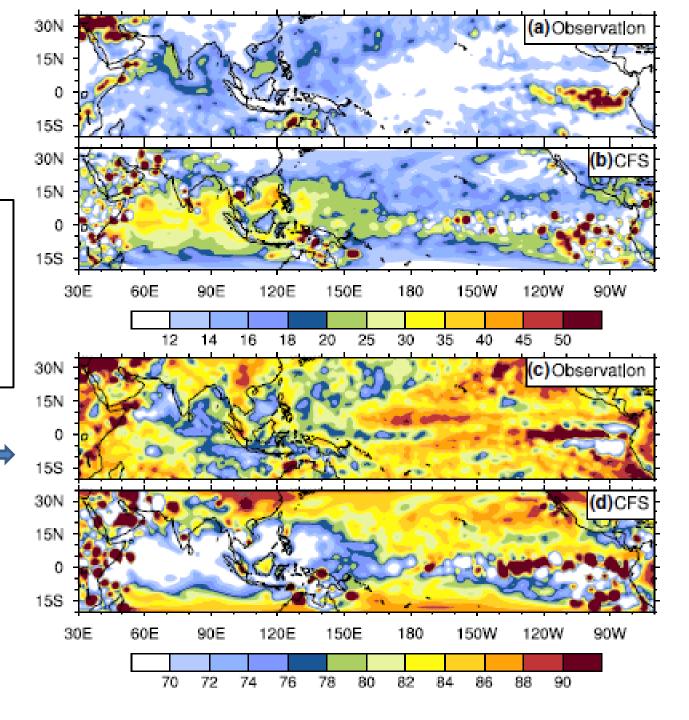
GPCP; b) ratio of ISO scale (10-90 day bandpassed) variance to total variance in GPCP; c) ratio of ISO scale variance to synoptic scale variance in GPCP; d) ratio of synoptic scale variance to total variance in CFSv2. e) Ratio of ISO scale variance to total variance in CFSv2: f) ratio of TSO scale variance to synoptic scale

Abhik et al. 2015

CFSv2 T382 ISO 10-90 days _____ variance

Take away:
The CFS shows
generally poor
variance in
synoptic scale

Synoptic variance
(2-10 Days)
CFSv2 T382
overestimates ISO
and
underestimates
Synoptic variance
over tropics



Flowchart of GEFS

GDAS

EnKF – GSI Hybrid Data Assimilation System

Ensemble Initialization method: Ensemble Kalman Filter (EnKF) scheme.

The 6-hr forecasts from the previous cycle

Analysis (Control)

20

Perturbed

members

Tropical Storm Relocation (if storm is present)

Centering of the perturbations on the ensemble control analysis (Distributes the spread around analysis instead of Ensemble Mean

POST PROCESSING 240 hr (10 days) forecast

Resolution: 0.125°x0.125°

6 hr interval

Products: 21 members, Ensemble mean, Ensemble Spread

FORECAST: 21 members runs for 192 hrs (8 days) GFS Semi-Lagrangian T1534 (approx 12 km at equator); L64 vertical resolution.

The stochastic total tendency perturbation (STTP) to enhance model uncertainty

The Global (Ensemble) Forecast Model

Flowchart of deterministic GFS

GDAS EnKF – GSI Hybrid Data Assimilation System

Analysis(Control)

FORECAST: GFS Semi-Lagrangian T1534 (approx 12 km at equator) L64 vertical resolution, runs for 240 hrs (10 days)

POST PROCESSING

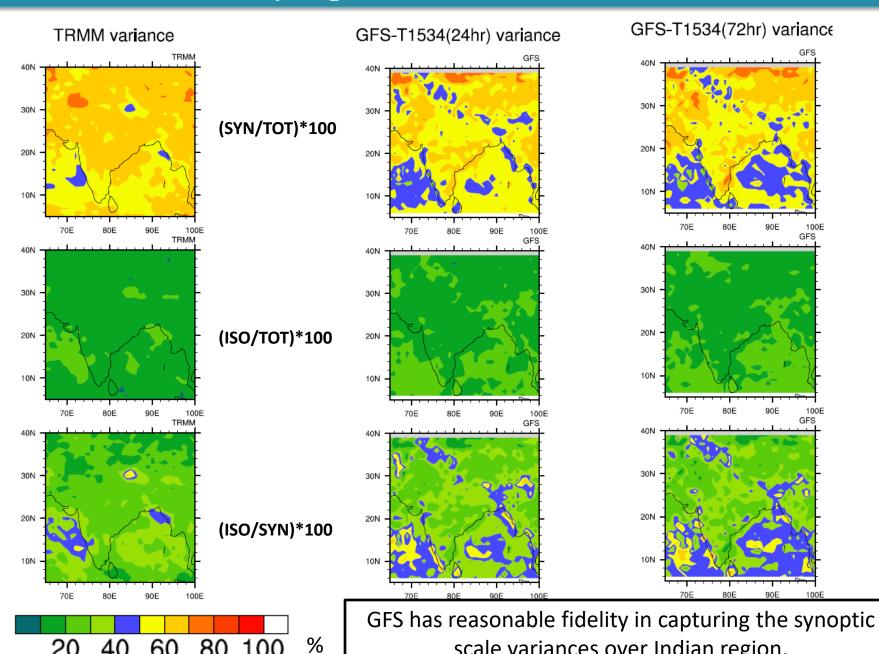
24ohr (10 days) forecast

Resolution: Regular grid and Gaussian grid at different resolutions

0.125°x0.125°

What about High Res. GFS (T1534~12.5 km)

Synoptic scale variance



scale variances over Indian region.

20

60

80 100

Further status of CFS/GFS





CFSv2 T382

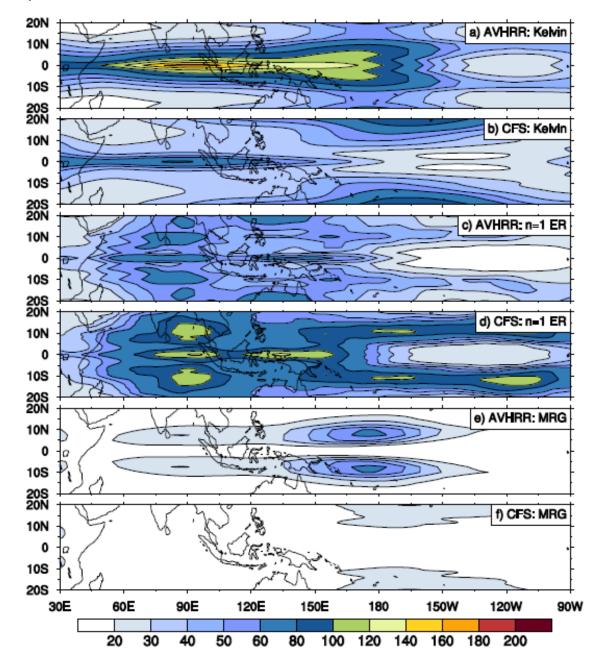


Fig. 13: Distribution of boreal summer time OLR variance (W² m⁻⁴) of (a), (b) Kelvin; (c), (d) n=1 ER and (e), (f) MRG waves for AVHRR and CFS.

Abhik et al., 2015

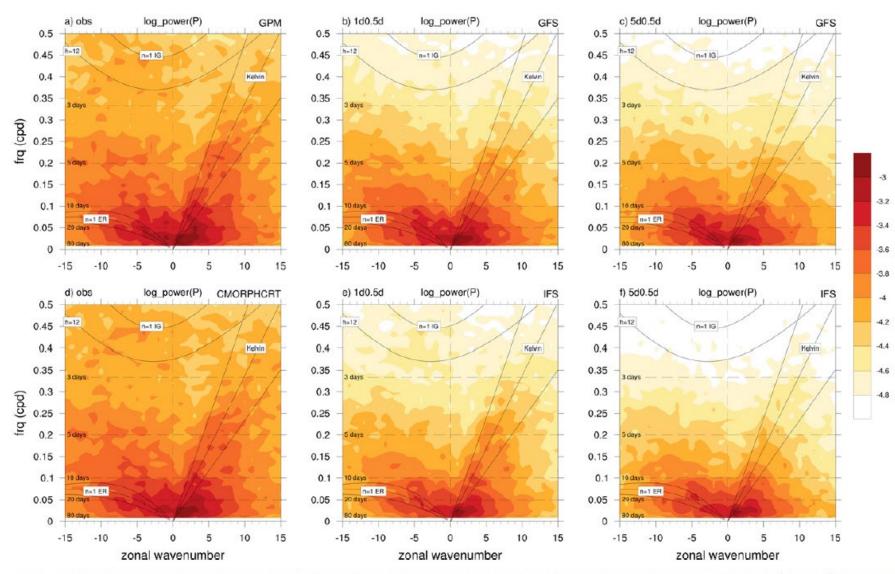


FIG. 9. Zonal wavenumber and frequency power spectra of symmetric rain rates about the equator averaged from 15°S to 15°N for the period January 2015–March 2016 of (a) GPM, (b) GFS 1d0.5d, (c) GFS 5d0.5d, (d) CMORPH, (e) IFS 1d0.5d, and (f) IFS 5d0.5d. Dispersion curves shown are for equatorial waves as in Wheeler and Kiladis (1999), for equivalent depths of 12, 25, and 50 m.

GFS and IFS

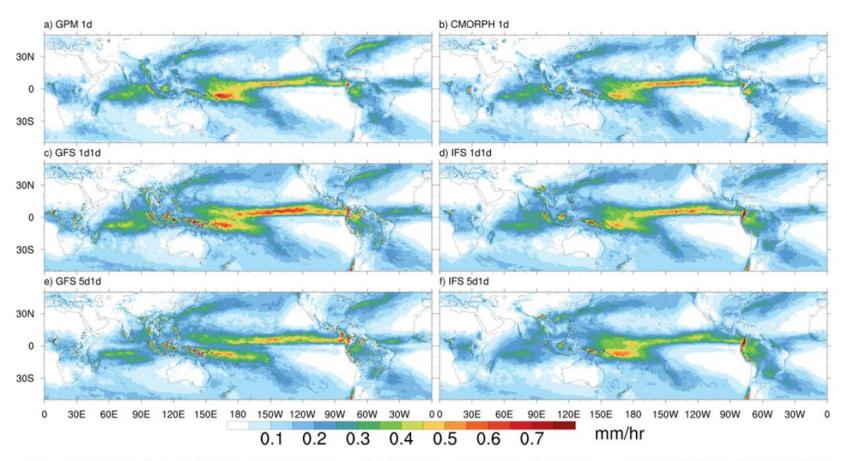


FIG. 3. Mean daily precipitation rate for the period January 2015–March 2016 from the (a) GPM, (b) CMORPH, (c) NCEP GFS day-1 forecast (1d1d), (d) ECMWF IFS day-1 forecast (1d1d), (e) NCEP GFS day-5 forecast (5d1d), and (f) IFS day-5 forecast (5d1d).

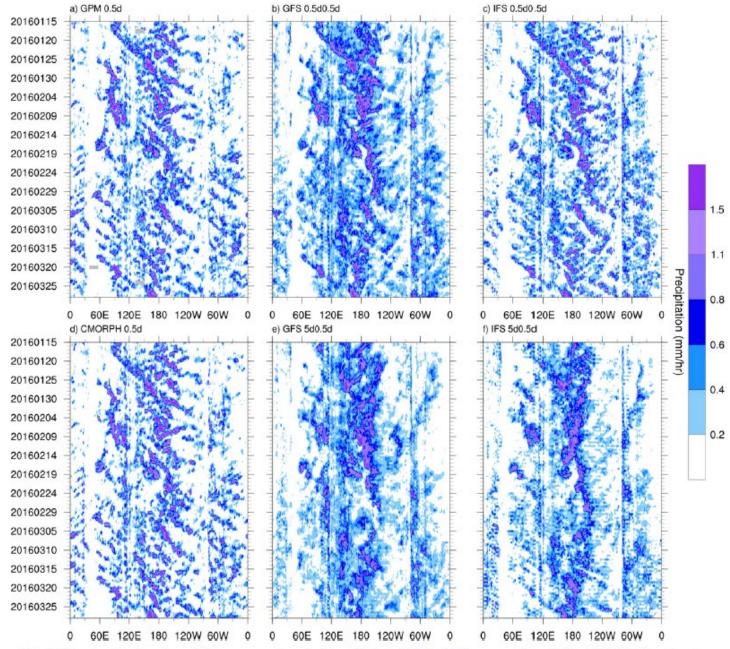


FIG. 1. Time-longitude section of 12-h average rain rates from 15 Jan to 25 Mar 2016 averaged from 5°S to 5°N. Satellite estimates are shown for (a) GPM and (d) CMORPH, and 12-h forecasts are shown for (b) the NCEP GFS and (c) the ECMWF IFS, and 120-h forecasts are shown for (e) the NCEP GFS and (f) the ECMWF IFS.

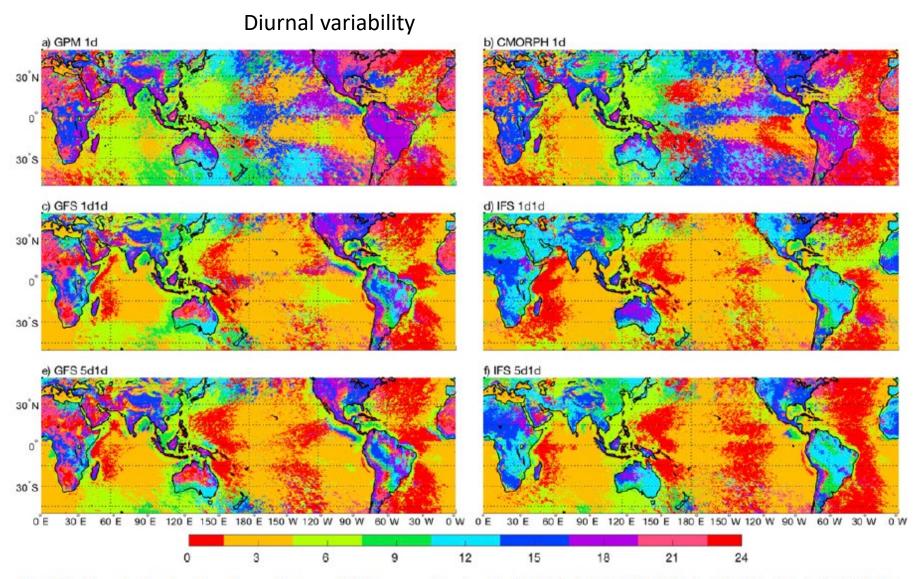
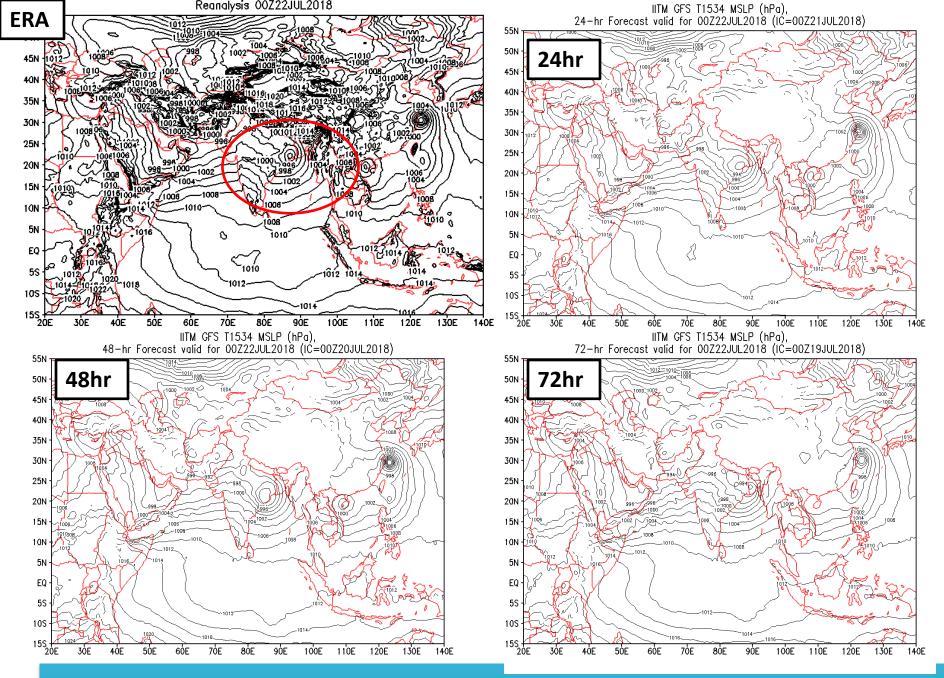


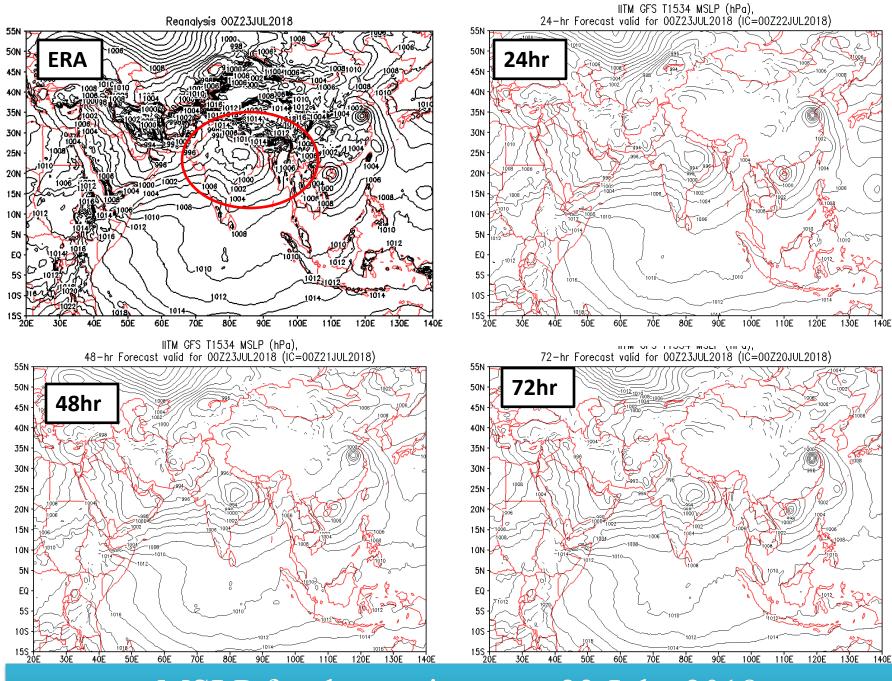
Fig. B1. Panels display the diurnal phase (LST hour of day) of (a) GPM, (b) CMORPH, (c) GFS 1d1d, (d) IFS 1d1d, (e) GFS 5d1d, and (f) IFS 5d1d.

Two questions

- Whether does the GFS capture the LPS and what lead?
- Fidelity to capture Transition from lows to depression

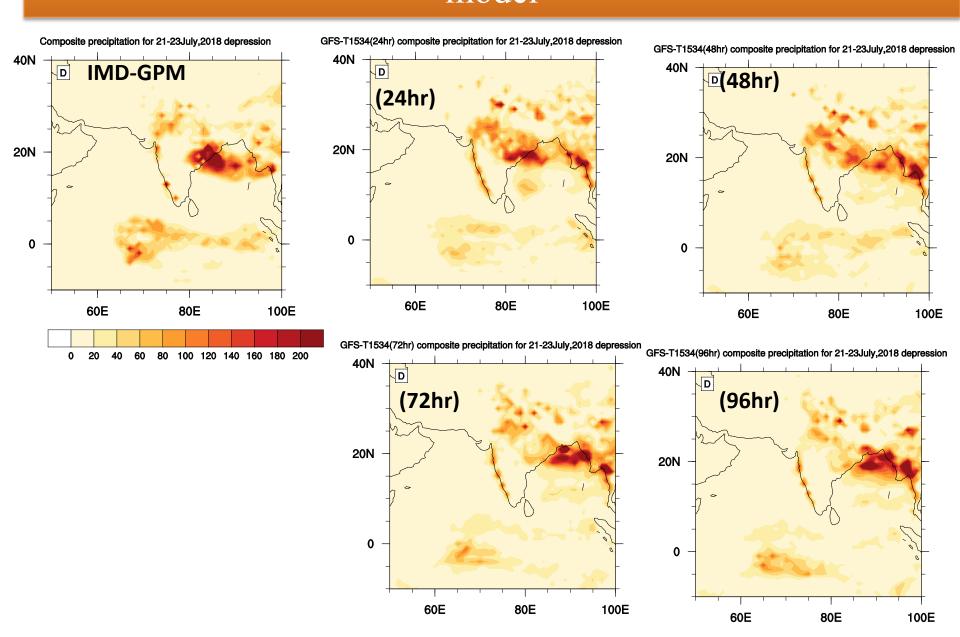


MSLP for depression case:22 July, 2018

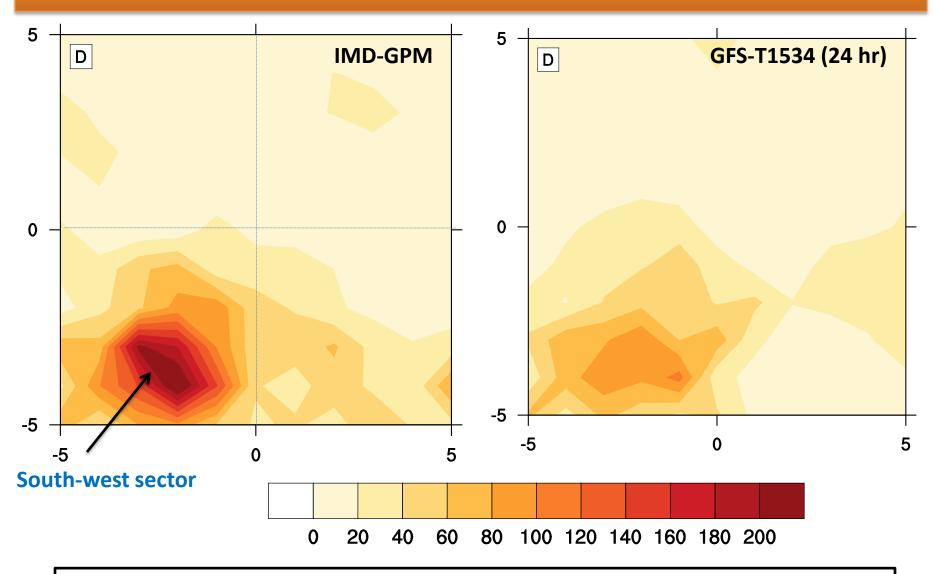


MSLP for depression case:23 July, 2018

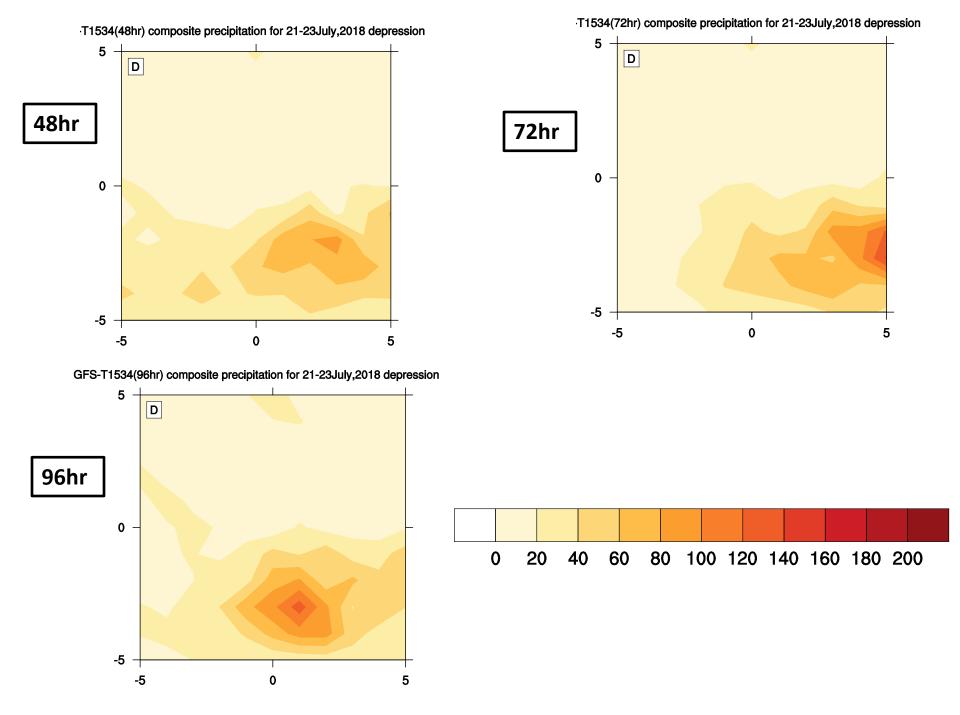
3 day accumulated precipitation based on observation and model



Composite precipitation for 21-23 July,2018 events based on observation and model



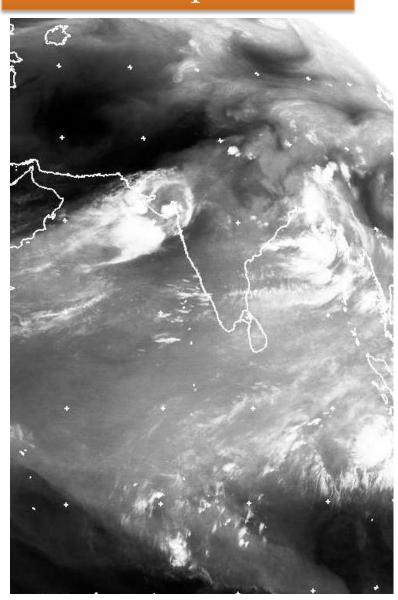
Positive(Negative) in x axis means to the east/west from the centre of the system. Positive(Negative) in y axis means to the north/south to the centre of the system



- > One may argue, the case shown earlier may be a random events where the model is able to capture the depression with good lead time.
- > To see the models systematic performance, we have analyzed data from 2001 to 2010 from observation and as well as from model.

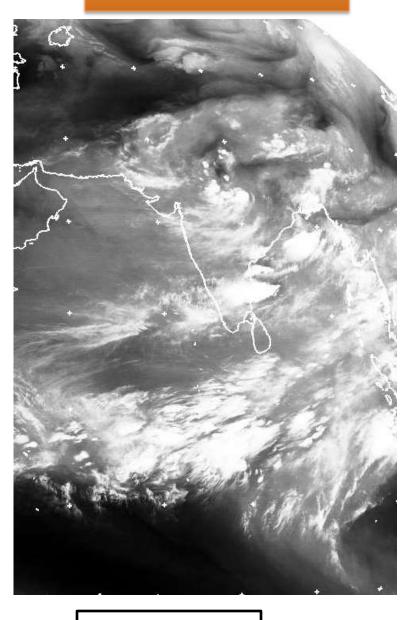
➤ We have identified 34 cases where low pressure system has intentensified into depressions and 73 cases where low pressure system was not able to intensify. The composite structure of the dynamical parameters based on observation and model are plotted.

Low to depression



Meteosat VISSR (IODC) 057.0E Image

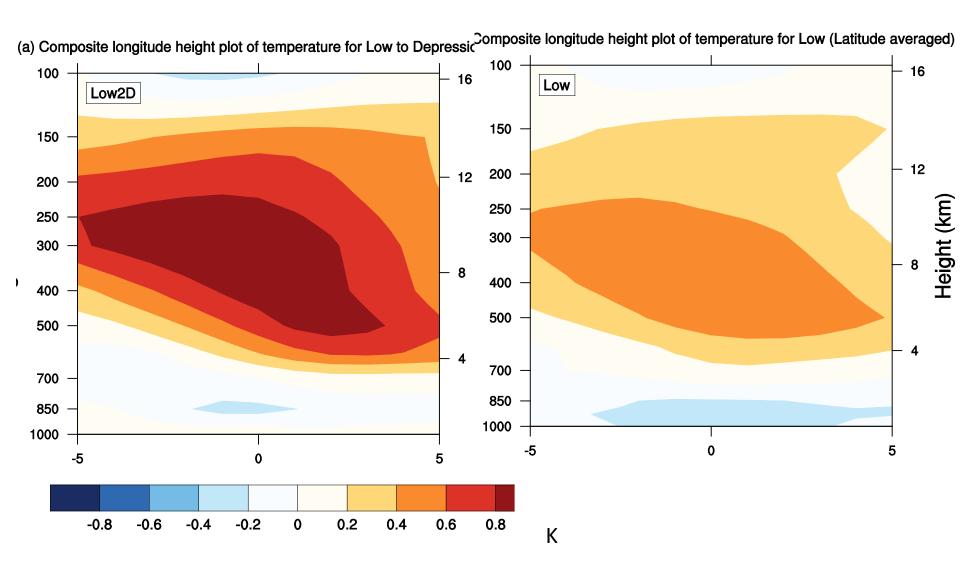
Low



14-18 Sep, 2008

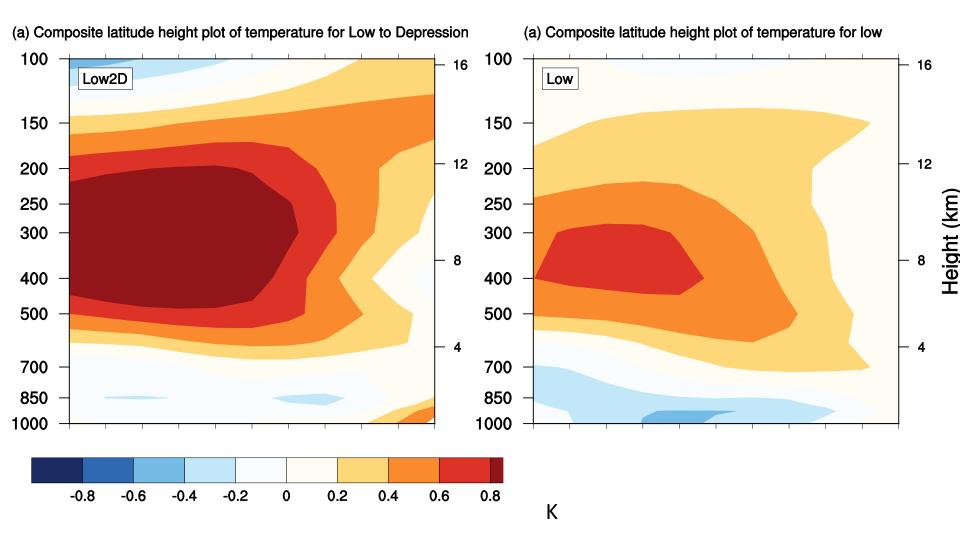
07-12 July, 2008

Longitude height plot of anomalous temperature (latitude averaged)



Positive(Negative) in x axis means to the east/west from the centre of the system.

Latitude height plot of anomalous temperature (Lon. averaged)



Positive(Negative) in x axis means to the north/south to the centre of the system

Longitude height plot of anomalous temperature

200

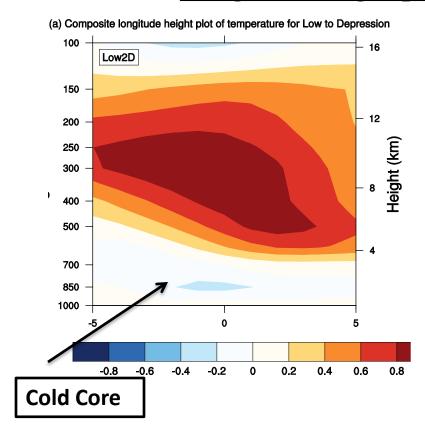
250

300

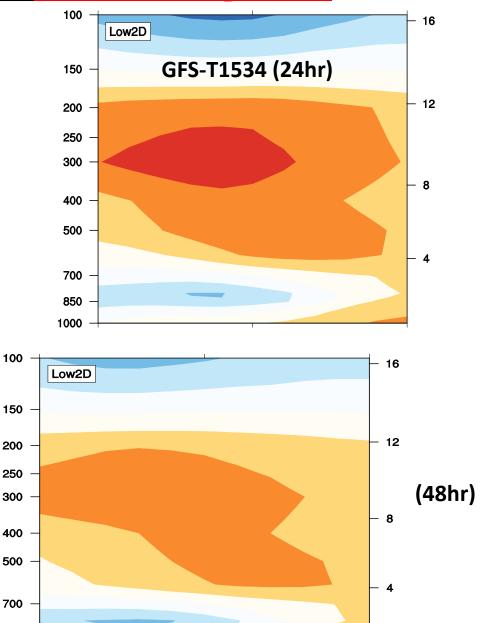
400

500

850 1000

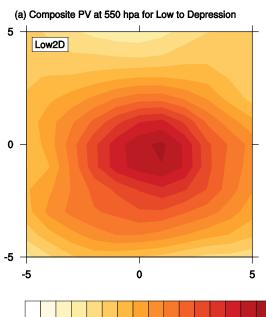


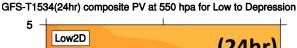
Positive(Negative) in x axis means to the east/west from the centre of the system.

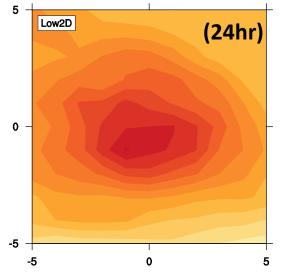


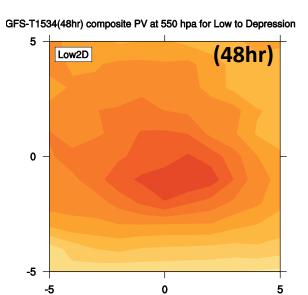
Potential vorticity (low to depression)











Positive(Negative) in x axis means to the east/west from the centre of the system.

4.2

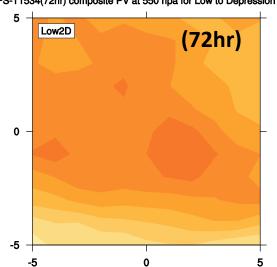
5.4

5.8

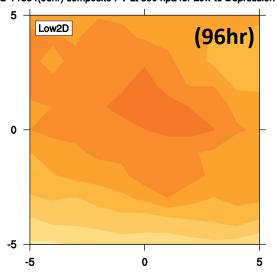
3.8

Positive(Negative) in y axis means to the north/south to the centre of the system



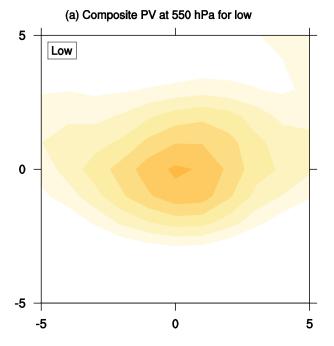


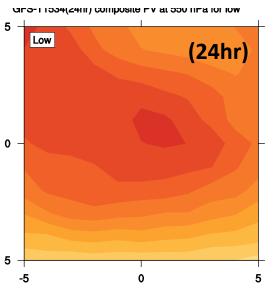
GFS-T1534(96hr) composite PV at 550 hpa for Low to Depression

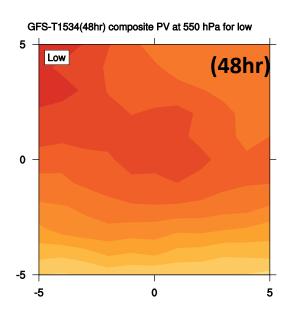


ERA

Same for low

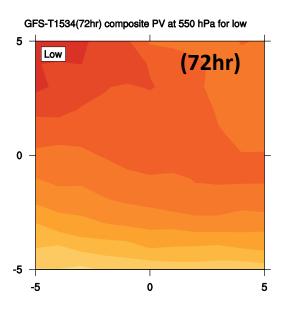


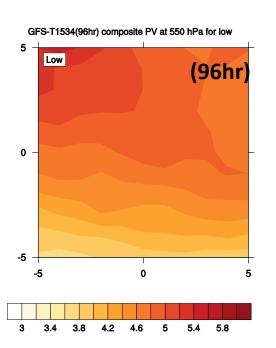




Positive(Negative) in x axis means to the east/west from the centre of the system.

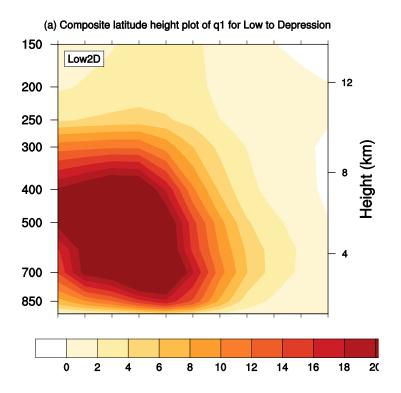
Positive(Negative) in y axis means to the north/south to the centre of the system

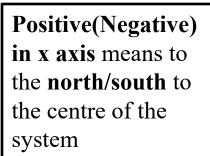


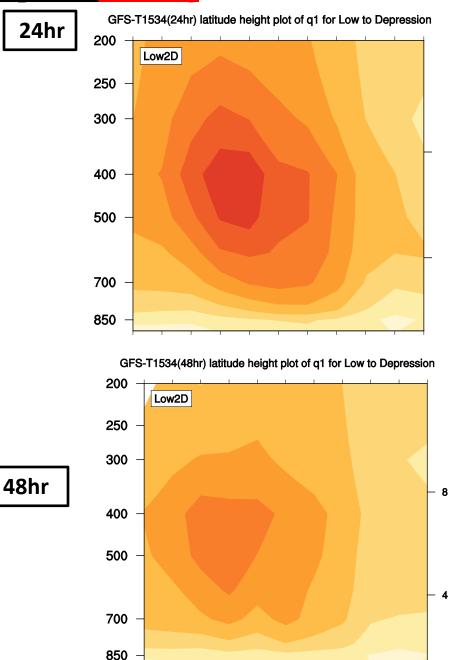


Latitude height plot of heating

ERA

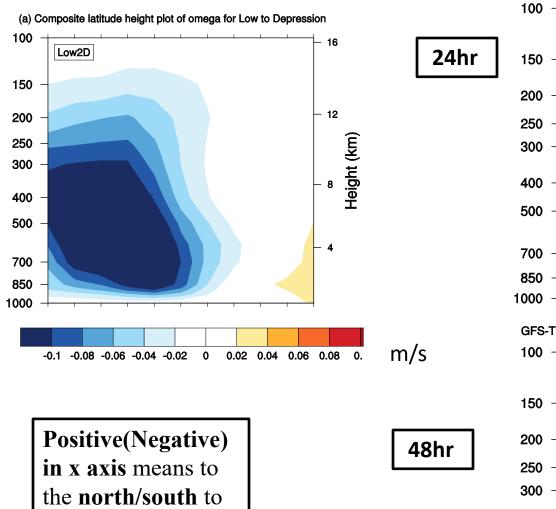






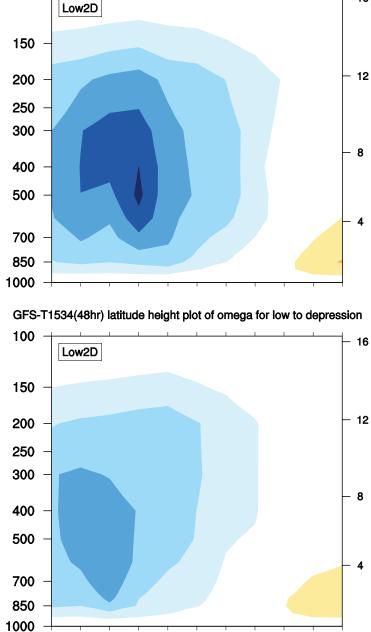
Latitude height plot of omega

ERA



the centre of the

system

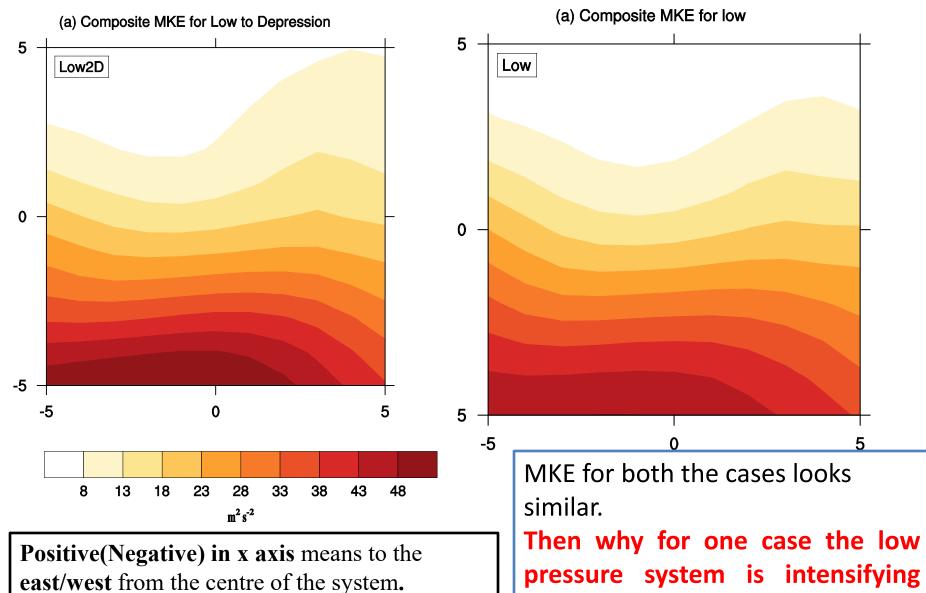


GFS-T1534(24hr) latitude height plot of omega for low to depression

16

Energetics analysis for low and depressions study

Mean kinetic energy (MKE) at 850 hpa level

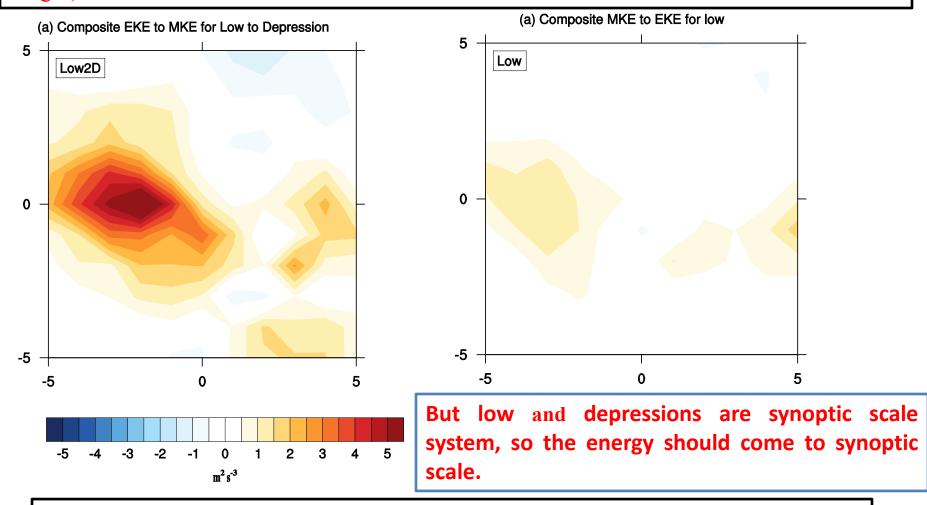


and other case it fails to intensify

Positive(Negative) in y axis means to the north/south to the centre of the system

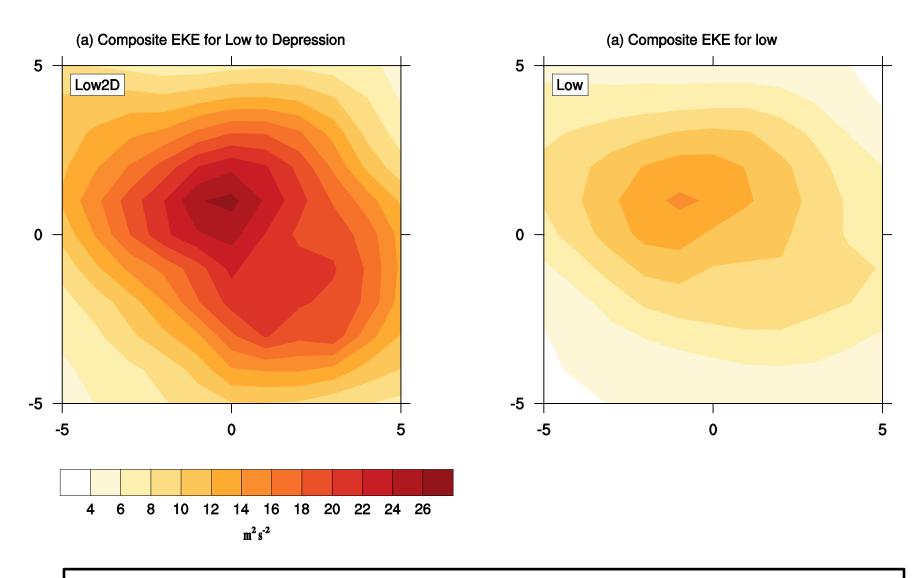
MKE to EKE conversion

MKE to EKE conversion is through the interaction between mean flow and high-frequency disturbances. Here EKE contains all the scale less than seasonal mean i.e synoptic scale (2-10 days), ISO scale (10-90 days) and low frequency background state (periods 90 days or longer).



Positive(Negative) in x axis means to the east/west from the centre of the system. Positive(Negative) in y axis means to the north/south to the centre of the system

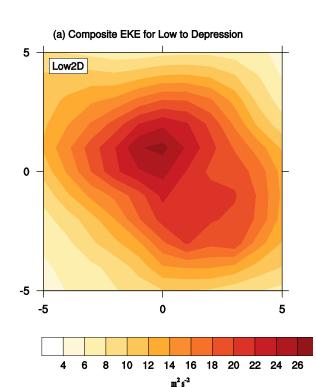
Synoptic scale eddy kinetic energy



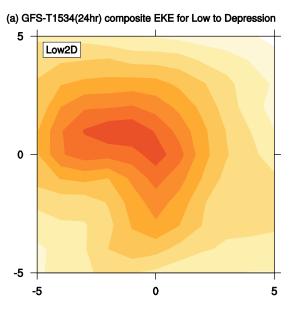
Positive(Negative) in x axis means to the east/west from the centre of the system. Positive(Negative) in y axis means to the north/south to the centre of the system

ERA

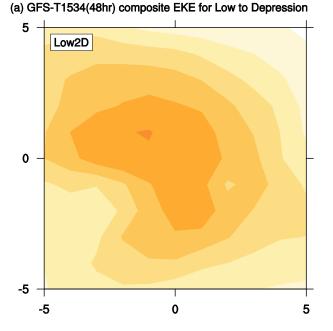
Synoptic scale eddy kinetic energy (low to depression)



GFS-T1534 (24hr)



GFS-T1534 (48hr)

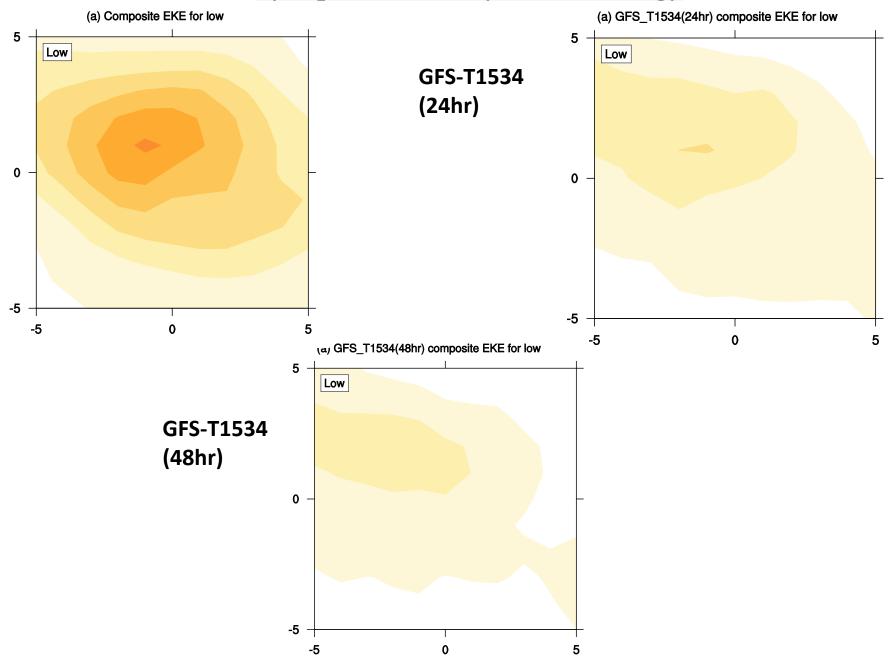


Positive(Negative) in x axis means to the east/west from the centre of the system.

Positive(Negative) in y axis means to the north/south to the centre of the system

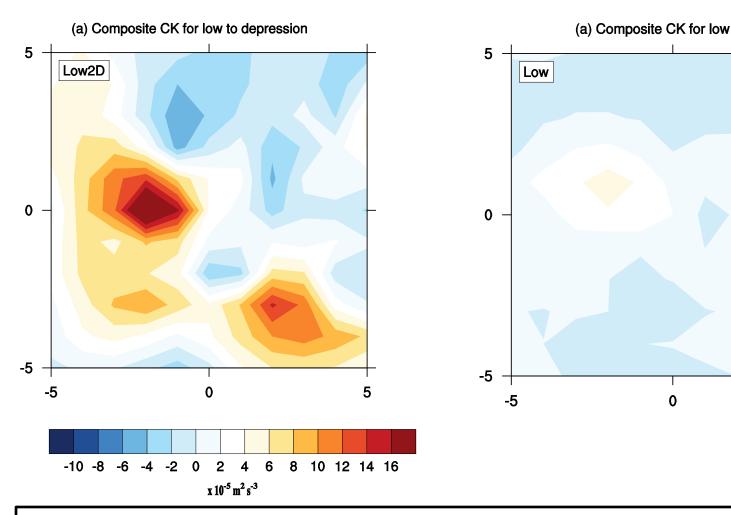


Synoptic scale eddy kinetic energy(low)

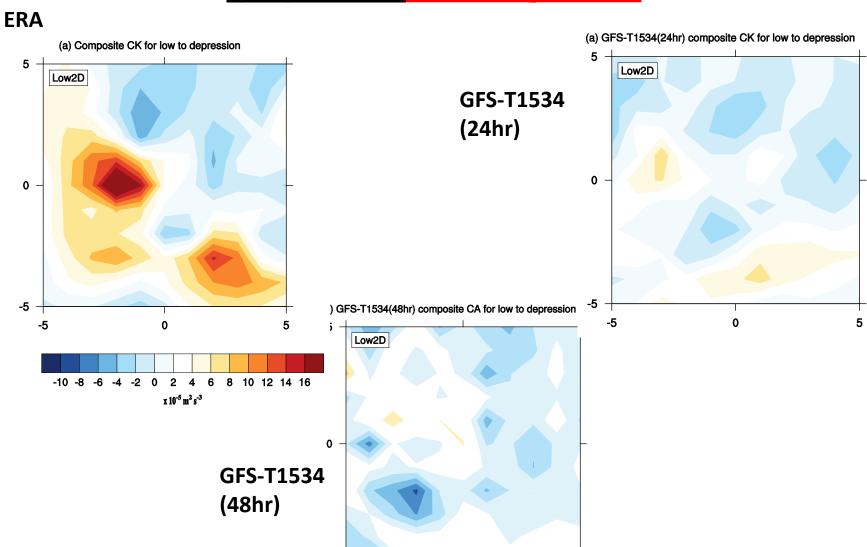


The processes that contribute to synoptic scale EKE

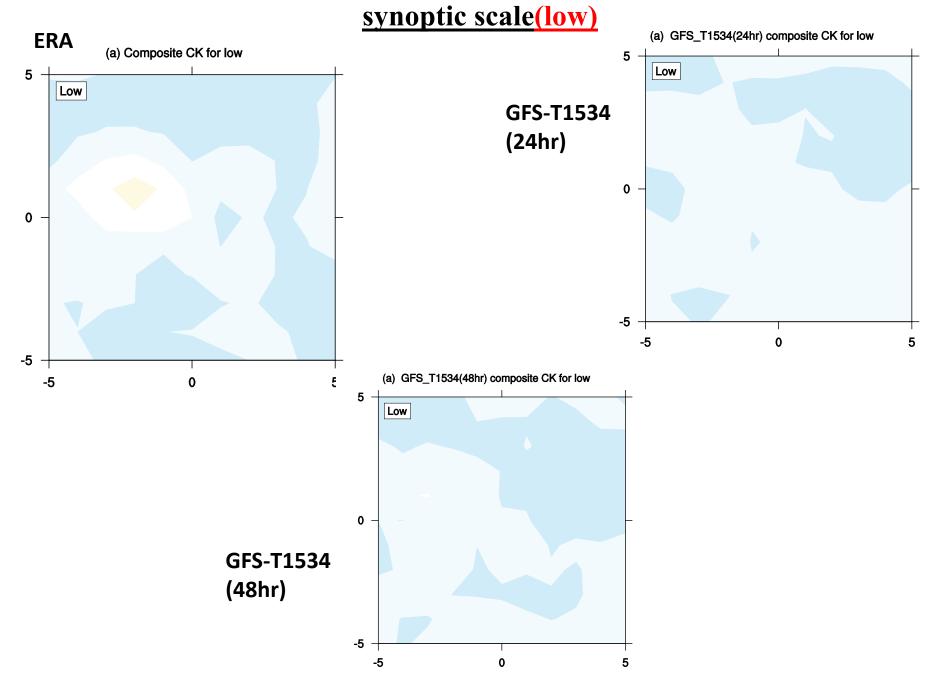
Barotropic energy Conversion from low frequency background state (LFBS) and ISO scale to the synoptic scale



Barotropic energy Conversion from LFBS and ISO scale to the synoptic scale (low to depression)

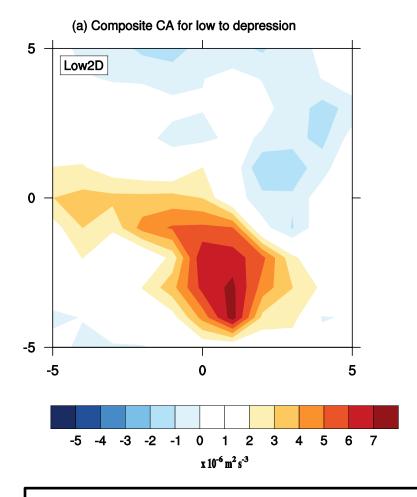


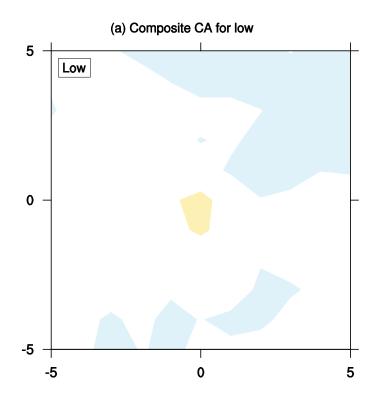
Barotropic energy Conversion from LFBS and ISO scale to the



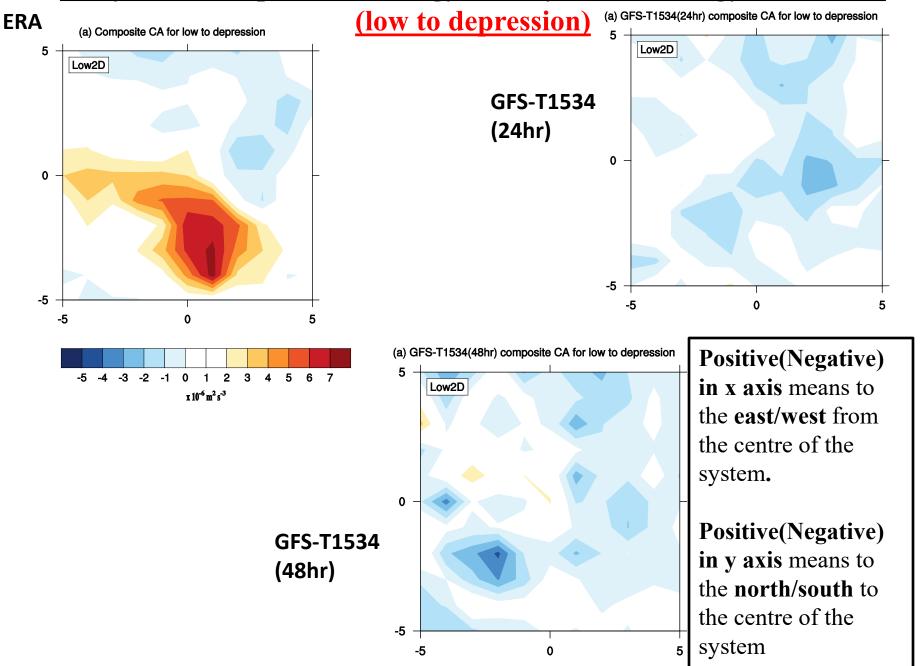
Eddy Available potential energy to eddy kinetic energy conversion (CA)

$$CA = -\frac{R}{p} \overline{\omega' T'},$$

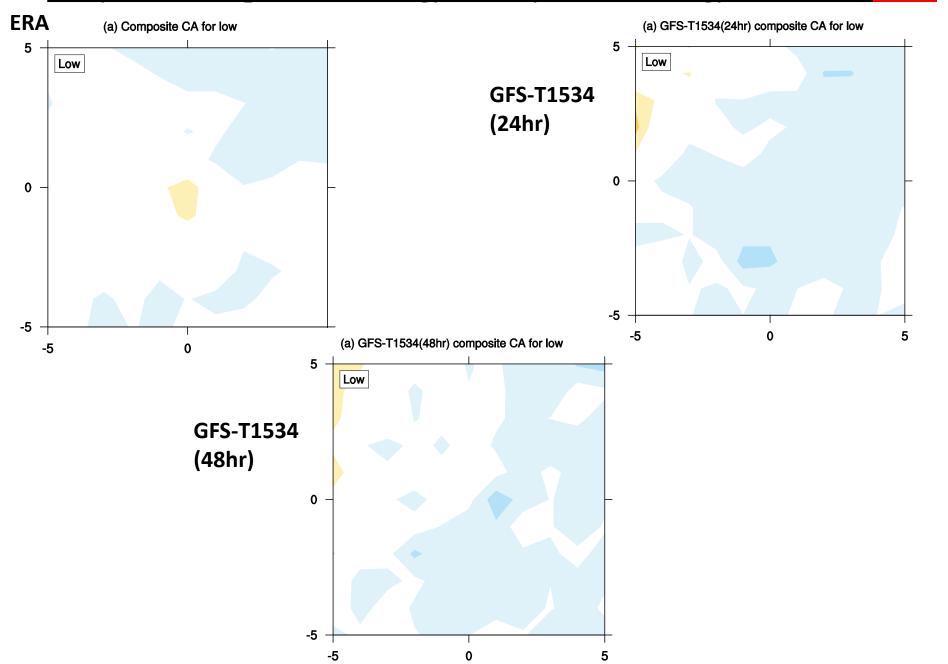




Eddy Available potential energy to eddy kinetic energy conversion



Eddy Available potential energy to eddy kinetic energy conversion(low)



Summary

 Fidelity of model in generating EKE and APE to EKE during Low2Deperession needs further improvement to improve the forecast with longer lead.

Model moist process needs further improvement

Higher resolution has shown improvement.

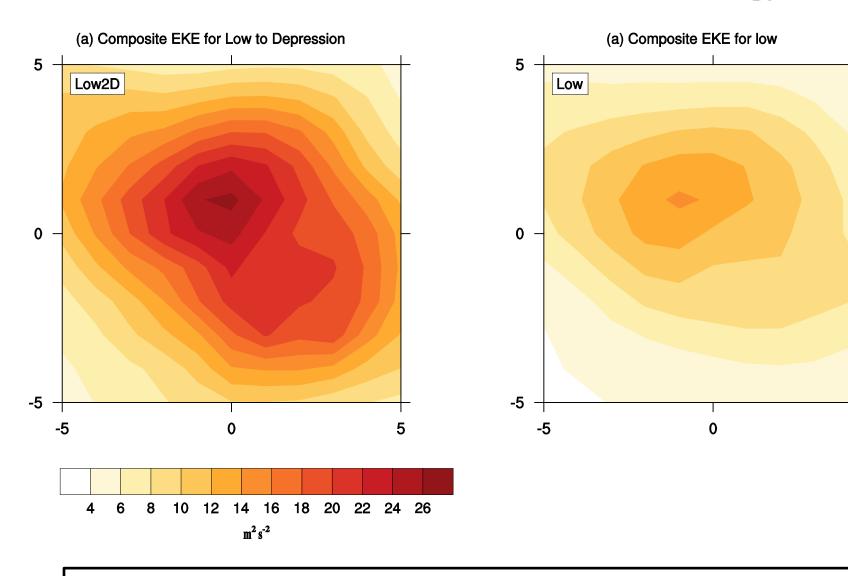
Thank You!





Synoptic scale eddy kinetic energy

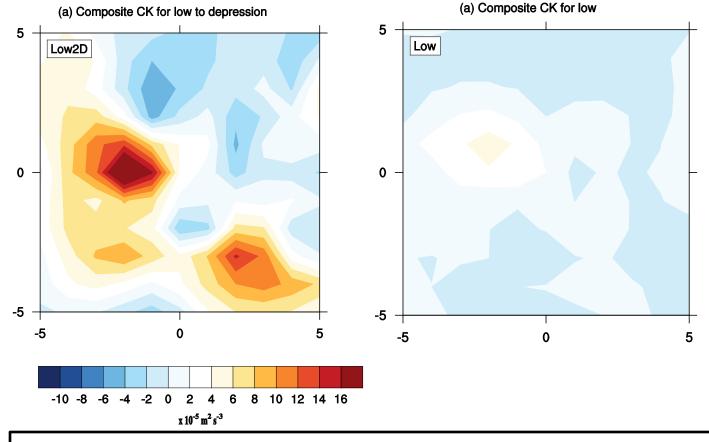
$$[(u'^2 + v'^2)/2]$$



Barotropic energy Conversion from low frequency background state (LFBS) and ISO scale to the synoptic scale

$$\overline{V'.\left[\left(\overline{\overline{\mathbf{V}}} + \tilde{\mathbf{V}} + \mathbf{V}'\right).\mathbf{\nabla}\right]\overline{\overline{\mathbf{V}}}} - \overline{V'.\left[\left(\overline{\overline{\mathbf{V}}} + \tilde{\mathbf{V}} + \mathbf{V}'\right).\mathbf{\nabla}\right]\tilde{\mathbf{V}}}$$

where double overbar means LFBS field, a tilted overbar means intra-seasonal component and prime means synopticscale field.



A new EKE diagnostic tool for examining the eddy-ISO interaction (Hsu et al. 2011, Sarkar et al. 2018)

A dependent variable is decomposed into three components- the low frequency background state (LFBS) which consist of periods 90 day or longer, intraseasonal component (10-90 days) and synoptic scale component (lower than 10 days). Any variable 'V' can be decomposed as- $V = \nabla + \tilde{V} + V'$ ------(1) Where double overbar means LFBS field, a tilted overbar means intraseasonal component and prime means synoptic-scale field.

$$\frac{\partial K'}{\partial t} = -u' \left(\frac{\partial \overline{u}}{\partial t} + \frac{\partial \widetilde{u}}{\partial t} \right) - v' \left(\frac{\partial \overline{v}}{\partial t} + \frac{\partial \widetilde{v}}{\partial t} \right) - u' (\overline{u} + \widetilde{u} + u') \left(\frac{\partial \overline{u}}{\partial x} + \frac{\partial \widetilde{u}}{\partial x} + \frac{\partial u'}{\partial x} \right) - v' (\overline{u} + \widetilde{u} + u') \left(\frac{\partial \overline{v}}{\partial x} + \frac{\partial v}{\partial x} + \frac{\partial v'}{\partial x} \right) \\
- u' (\overline{v} + \widetilde{v} + v') \left(\frac{\partial \overline{u}}{\partial y} + \frac{\partial \widetilde{u}}{\partial y} + \frac{\partial u'}{\partial y} \right) - v' (\overline{v} + \widetilde{v} + v') \left(\frac{\partial \overline{v}}{\partial y} + \frac{\partial v}{\partial y} + \frac{\partial v'}{\partial y} \right) - u' (\overline{\omega} + \widetilde{\omega} + \omega') \left(\frac{\partial \overline{u}}{\partial p} + \frac{\partial \widetilde{u}}{\partial p} + \frac{\partial u'}{\partial p} \right) \\
- v' (\overline{\omega} + \widetilde{\omega} + \omega') \left(\frac{\partial \overline{v}}{\partial p} + \frac{\partial v'}{\partial p} + \frac{\partial v'}{\partial p} \right) - u' \left(\frac{\partial \overline{\phi}}{\partial x} + \frac{\partial \phi}{\partial x} + \frac{\partial \phi'}{\partial x} \right) - v' \left(\frac{\partial \overline{\phi}}{\partial y} + \frac{\partial \phi}{\partial y} + \frac{\partial \phi'}{\partial y} \right), \tag{2}$$

Then a low-frequency EKE budget equation may be derived as follows:

$$\frac{\partial \overline{K'}}{\partial t} = CK + CA + AM + AE + FG \tag{3}$$

$$CK = -\overline{V' \cdot [(\overline{V_3} + \tilde{V}_3 + V_3') \cdot \nabla_3]\overline{V}} - \overline{V' \cdot [(\overline{V_3} + \tilde{V}_3 + V_3') \cdot \nabla_3]\tilde{V}}$$

$$= -\left(\overline{u'\overline{u}} \frac{\partial \overline{u}}{\partial x} + \overline{v'\overline{u}} \frac{\partial \overline{u}}{\partial x} + \overline{u'\overline{v}} \frac{\partial \overline{u}}{\partial y} + \overline{v'\overline{v}} \frac{\partial \overline{u}}{\partial y} + \overline{v'\overline{w}} \frac{\partial \overline{u}}{\partial p} + \overline{v'\overline{w}} \frac{\partial \overline{u}}{\partial p} + \overline{u'u} \frac{\partial \overline{u}}{\partial x} + \overline{v'u} \frac{\partial \overline{u}}{\partial x} + \overline{u'v} \frac{\partial \overline{u}}{\partial y} + \overline{u'\overline{w}} \frac{\partial \overline{u}}{\partial p} + \overline{u'\overline{w}} \frac{\partial \overline{u}}{\partial y} + \overline{u'$$

Apply a 10-day low-pass filtering operator (denoted by a single overbar) to the perturbation EKE equation above. The following terms can be dropped:

$$-\overline{u'\left(\frac{\partial\overline{\overline{u}}}{\partial t} + \frac{\partial\widetilde{u}}{\partial t}\right)} = -\overline{u'\frac{\partial\overline{\overline{u}}}{\partial t}} = 0,$$

$$-\overline{v'\left(\frac{\partial\overline{\overline{v}}}{\partial t} + \frac{\partial\widetilde{v}}{\partial t}\right)} = -\overline{v'\frac{\partial\overline{\overline{v}}}{\partial t}} = 0,$$

$$-\overline{u'\left(\frac{\partial\overline{\overline{\phi}}}{\partial x} + \frac{\partial\widetilde{\phi}}{\partial x}\right)} = -\overline{u'\frac{\partial\overline{\phi}}{\partial x}} = 0, \text{ and}$$

$$-\overline{v'\left(\frac{\partial\overline{\overline{\phi}}}{\partial y} + \frac{\partial\widetilde{\phi}}{\partial y}\right)} = -\overline{v'\frac{\partial\overline{\phi}}{\partial y}} = 0.$$

$$\begin{split} \mathrm{CA} &= -\frac{R}{p} \overline{T' \omega'}, \\ \mathrm{AM} &= \mathrm{AMm} + \mathrm{AMi} = -\overline{\overline{\mathbf{V}}_3 \cdot \nabla_3 K'} - \overline{\tilde{\mathbf{V}}_3 \cdot \nabla_3 K'}, \\ \mathrm{AE} &= -\overline{\mathbf{V}_3' \cdot \nabla_3 K'}, \quad \text{and} \\ \mathrm{FG} &= -\overline{\nabla_3 \cdot (\mathbf{V}_3' \phi')} \end{split}$$

where a single overbar represents the 10-day low-pass filtering operator, $\overline{K'}$ is the low-frequency EKE (including both the LFBS and ISO components), \mathbf{V} is the horizontal velocity vector, ∇ is the horizontal gradient operator (the subscript 3 represents the three-dimensional components), R is the gas constant for dry air, and T is temperature.

Meaning of Each Term

CK – Conversion from LFBS and ISO scale to synoptic scale system.

CA – Eddy Available potential Energy (EAPE) to Eddy Kinetic energy conversion(EKE).

AM- The advection of EKE by both LFBS and ISO flows.

AE- The advection of EKE by Synoptic scale eddy.

FG- Generation of EKE through convergence of eddy geopotential.